

# Initial-Boundary Value Problem for Some Viscous Incompressible Flow

ある非圧縮粘性流に対する初期値境界値問題

伊 藤 成 治\*

Shigeharu ITOH

**Abstract.** We prove the local existence of weak solutions to the initial-boundary value problem with a nonnegative initial density for a nonhomogeneous viscous incompressible fluid.

**§1. Introduction.** The motion of a nonhomogeneous viscous incompressible fluid is described by the system of equations for the density  $\rho(t, x)$ , the velocity  $v(t, x) = (v^1(t, x), v^2(t, x), v^3(t, x))$ , the pressure  $p(t, x)$  and the absolute temperature  $\theta(t, x)$  (cf. [1]):

$$(1.1) \quad \begin{cases} \rho_t + (v \cdot \nabla) \rho = 0, \\ \rho [v_t + (v \cdot \nabla) v] + \nabla p = \mu \Delta v + \rho f, \\ \nabla \cdot v = 0, \\ c_V \rho [\theta_t + (v \cdot \nabla) \theta] = \kappa \Delta \theta + 2\mu D:D, \end{cases}$$

where  $f(t, x) = (f^1(t, x), f^2(t, x), f^3(t, x))$  is the outer force and  $D$  is the velocity deformation tensor with the elements  $D_{ij} = \frac{1}{2} \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right)$ ,  $i, j = 1, 2, 3$  and  $D:D = \sum_{i,j=1}^3 D_{ij} D_{ij}$ . We assume that  $\mu$  (the coefficient of viscosity),  $c_V$  (the specific heat at constant volume) and  $\kappa$  (the coefficient of heat conduction) are positive constants.

Let  $\Omega$  be a bounded open set in  $\mathbb{R}^3$  with a smooth boundary  $\partial\Omega$ . We consider the above system under the following initial-boundary condition:

$$(1.2) \quad \begin{cases} (\rho(0, x), v(0, x), \theta(0, x)) = (\rho_0(x), v_0(x), \theta_0(x)), x \in \Omega, \\ v|_{\partial\Omega} = 0, \theta|_{\partial\Omega} = \bar{\theta}, t > 0, \end{cases}$$

where  $\bar{\theta}$  is a fixed positive constant and we always assume that the compatibility conditions are satisfied. We note that the problem (1.1), (1.2) is rewritten to the problem (1.1),

\* 弘前大学教育学部数学科教室

Department of Mathematics, Faculty of Education, Hirosaki University

$$(1.3) \quad \begin{cases} (\rho(0, x), v(0, x), \theta(0, x)) = (\rho_0(x), v_0(x), \theta_0(x) - \bar{\theta}), \\ (v, \theta)|_{\partial\Omega} = 0, t > 0, \end{cases}$$

by the change of variables  $(\rho, v, \theta) \rightarrow (\rho, v, \theta + \bar{\theta})$ . Let us term the problem (1.1), (1.3) IBP.

We are much interested in the case of  $\rho_0 \geq 0$ , because in the usual result, it seems that the assumption that  $\rho_0(x)$  is strictly positive is essential.

In this paper we show the existence of a weak solution to IBP, in the sense of Definition in §2, under suitable assumptions.

**§2. Statement of Result.** For  $s \in \mathbb{R}$ ,  $H^s(\Omega)$  denotes the usual Sobolev space. Let us introduce  $C_\sigma^\infty(\Omega) = \{u \in C_0^\infty(\Omega)^3; \nabla \cdot u = 0\}$  and  $H_\sigma^s(\Omega) = \text{closure of } C_\sigma^\infty(\Omega) \text{ in } H^s(\Omega)^3$ .

Next we give the definition of a weak solution to IBP.

**Definition.** The functions  $\rho(t, x)$ ,  $v(t, x) = (v^1(t, x), v^2(t, x), v^3(t, x))$  and  $\theta(t, x)$  called a weak solution to IBP, if  $\rho(t, x) \in L^\infty([0, T] \times \Omega)$ ,  $v(t, x) \in L^2(0, T; H_\sigma^1(\Omega))$  and  $\theta(t, x) \in L^2(0, T; H_0^1(\Omega))$  and if the integral identities

$$(2.1) \quad \int_0^T \int_\Omega (\rho \varphi_t + \sum_{j=1}^3 \rho v^j \varphi_{x_j}) dx dt + \int_\Omega \rho_0(x) \varphi(0, x) dx = 0,$$

$$(2.2) \quad \int_0^T \int_\Omega (\rho v \cdot \Phi_t + \sum_{j=1}^3 \rho v^j v \cdot \Phi_{x_j} - \mu \sum_{j=1}^3 v_{x_j} \cdot \Phi_{x_j} + \rho f \cdot \Phi) dx dt \\ + \int_\Omega \rho_0(x) v_0(x) \cdot \Phi(0, x) dx = 0$$

and

$$(2.3) \quad \int_0^T \int_\Omega (c_V \rho \theta \varphi_t + c_V \sum_{j=1}^3 \rho v^j \theta \varphi_{x_j} - \kappa \sum_{j=1}^3 \theta_{x_j} \varphi_{x_j} - 2\mu D : D\varphi) dx dt \\ + \int_\Omega c_V \rho_0(x) (\theta_0(x) - \bar{\theta}) \varphi(0, x) dx = 0$$

hold for any  $\varphi \in C^1(0, T; H^1(\Omega))$  and  $\Phi \in C^1(0, T; H_\sigma^1(\Omega))$  such that  $\varphi(T, x) = 0$  and  $\Phi(T, x) = 0$ .

Now we can state our result.

**Theorem.** *Suppose that  $0 \leq \rho_0(x) \leq M$ ,  $v_0(x) \in H_\sigma^1(\Omega)$ ,  $\theta_0(x) - \bar{\theta} \in L^2(\Omega)$  and  $f(t, x) \in L^2(0, T; L^2(\Omega)^3)$ . Then there exists a weak solution for some  $T' \in (0, T]$  such that  $\rho(t, x)$*

$\in L^\infty([0, T'] \times \Omega)$ ,  $v(t, x) \in L^\infty(0, T'; H_\sigma^1(\Omega)) \cap L^2(0, T'; H^2(\Omega))$  and  $\theta(t, x) \in L^2(0, T'; H_0^1(\Omega))$ .

The proof is given in §§3-7.

**§3. Proof of Theorem** (first step). Let  $P$  be the projection of  $L^2(\Omega)^3$  onto  $H_\sigma^0(\Omega)$  and let us consider the eigenvalue problem:

$$(3.1) \quad \begin{cases} \mu P \Delta \psi_k + \lambda_k \psi_k = 0 & \text{in } \Omega, \\ \psi_k|_{\partial\Omega} = 0. \end{cases}$$

With respect to the properties of the operator  $\mu P \Delta$ , we refer to [2]. For example,

**Lemma 3.1.**  $\mu P \Delta$  is a self-adjoint operator in  $H_\sigma^0(\Omega)$  and its inverse is compact.

Therefore we find that

$$(3.2) \quad 0 < \lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_k \rightarrow \infty \text{ as } k \rightarrow \infty$$

and

$$(3.3) \quad \{\psi_k\}_{k=1}^\infty \text{ is an orthonormal system in } H_\sigma^0(\Omega).$$

Let  $\{\rho_{0m}(x)\}_{m=1}^\infty$  be a sequence of functions such that  $\rho_{0m}(x) \in C^1(\bar{\Omega})$ ,  $\frac{1}{m} \leq \rho_{0m}(x) \leq M + \frac{1}{m}$  and  $\rho_{0m}(x) \rightarrow \rho_0(x)$  in  $L^2(\Omega)$  and let  $\tilde{v}_m(t, x) = \sum_{k=1}^m \tilde{a}_{mk}(t) \psi_k(x)$ , where  $\tilde{a}_{mk}(t) \in C^0([0, T])$ ,  $k=1, \dots, m$ .

Now we consider the following Cauchy problem:

$$(3.4) \quad \begin{cases} \rho_{mt} + \sum_{j=1}^3 \tilde{v}_m^j \rho_{mj} = 0 \\ \rho_m(0, x) = \rho_{0m}(x). \end{cases}$$

Then we have

**Lemma 3.2.** There exists a number  $T_1 \in (0, T]$  such that (3.4) has a unique solution



**Lemma 4.1.** *There exists a number  $T_2 \in (0, T_1]$  such that (4.1) has a unique solution  $(a_{m1}(t), \dots, a_{mm}(t)) \in C^1([0, T_2])^m$ .*

If we set  $v_m(t, x) = \sum_{k=1}^m a_{mk}(t) \psi_k(x)$ , then we have

**Lemma 4.2.** *There exist a number  $T' \in (0, T_2]$  and constant  $c > 0$  which are independent of  $m$  such that*

$$(4.5) \quad \|\sqrt{\rho_m v_{mt}}\|_{L^2(0, T'; L^2(\Omega)^3)} + \|v_m\|_{L^\infty(0, T'; H_\sigma^1(\Omega))} \\ + \|v_m\|_{L^2(0, T'; H^2(\Omega)^3)} \leq c.$$

*Proof.* If we multiply (4.1) by  $\frac{d}{dt} a_{mj}(t)$  and sum over  $j=1, \dots, m$ , then we get that

$$(4.6) \quad \int_{\Omega} \rho_m |v_{mt}|^2 dx + \int_{\Omega} \rho_m \{ (v_m \cdot \nabla) v_m \} \cdot v_{mt} dx \\ + \frac{1}{2} \frac{d}{dt} \int_{\Omega} |\nabla v_m|^2 dx = \int_{\Omega} \rho_m f_m \cdot v_{mt} dx.$$

Next multiplying (4.1) by  $\lambda_j a_{mj}(t)$  and summing over  $j=1, \dots, m$ , then we obtain that

$$(4.7) \quad \int_{\Omega} |\mathbf{P}\Delta v_m|^2 dx = \int_{\Omega} \rho_m v_{mt} \cdot \mathbf{P}\Delta v_m dx \\ + \int_{\Omega} \rho_m \{ (v_m \cdot \nabla) v_m \} \cdot \mathbf{P}\Delta v_m dx - \int_{\Omega} \rho_m f_m \cdot \mathbf{P}\Delta v_m dx.$$

By the way, let  $u \in H_0^1(\Omega) \cap H^2(\Omega)$ , then for any  $\delta$  with  $0 \leq \delta \leq 1$  there exists a constant  $c_1 > 0$  dependent only on  $\delta$  and  $\Omega$  such that

$$(4.8) \quad \|u\|_{H^{1-\delta}(\Omega)} \leq c_1 \|\nabla u\|_{L^2(\Omega)}^{1-\delta} \|\Delta u\|_{L^2(\Omega)}^{\delta}$$

holds. Hence we find that

$$(4.9) \quad \int_{\Omega} |v_m|^2 |\nabla v_m|^2 dx \leq c_2 \|v_m\|_{H^{1+2/3}(\Omega)}^2 \|\nabla v_m\|_{L^2(\Omega)}^2 \\ \leq c_3 \|\nabla v_m\|_{L^2(\Omega)}^{8/3} \|\Delta v_m\|_{L^2(\Omega)}^{4/3} \\ \leq c_4 \|\nabla v_m\|_{L^2(\Omega)}^8 + \varepsilon_1 \|\mathbf{P}\Delta v_m\|_{L^2(\Omega)}^2,$$

where  $c_2$ ,  $c_3$  and  $c_4$  are independent of  $m$  and  $\varepsilon_1$  will be determined later on. Then we have

$$\begin{aligned}
(4.10) \quad & \frac{1}{2} \frac{d}{dt} \|\nabla v_m\|_{L^2(\Omega)}^2 + \|\sqrt{\rho m v m t}\|_{L^2(\Omega)}^2 \\
& \leq \frac{1}{2} \|\sqrt{\rho m v m t}\|_{L^2(\Omega)}^2 + \varepsilon_1 \|\mathbf{P}\Delta v_m\|_{L^2(\Omega)}^2 + c_5 \|\nabla v_m\|_{L^2(\Omega)}^8 + c_5 \|f_m\|_{L^2(\Omega)}^2
\end{aligned}$$

and

$$\begin{aligned}
(4.11) \quad & \|\mathbf{P}\Delta v_m\|_{L^2(\Omega)}^2 \leq \left(\frac{3}{4} + \varepsilon_1\right) \|\mathbf{P}\Delta v_m\|_{L^2(\Omega)}^2 + c_5 \|\sqrt{\rho m v m t}\|_{L^2(\Omega)}^2 \\
& + c_5 \|\nabla v_m\|_{L^2(\Omega)}^8 + c_5 \|f_m\|_{L^2(\Omega)}^2,
\end{aligned}$$

where  $c_5$  is independent of  $m$ .

Let  $\varepsilon = 1/4c_5$  and  $\varepsilon_1 = \varepsilon/8(\varepsilon + 1)$ , then (4.10) +  $\varepsilon$ (4.11) implies that

$$\begin{aligned}
(4.12) \quad & \frac{1}{2} \frac{d}{dt} \|\nabla v_m\|_{L^2(\Omega)}^2 + \frac{1}{4} \|\sqrt{\rho m v m t}\|_{L^2(\Omega)}^2 + \frac{\varepsilon}{8} \|\mathbf{P}\Delta v_m\|_{L^2(\Omega)}^2 \\
& \leq c_6 (\|\nabla v_m\|_{L^2(\Omega)}^8 + \|f_m\|_{L^2(\Omega)}^2),
\end{aligned}$$

where  $c_6$  is independent of  $m$ .

Therefore we find that there exist a number  $T' \in (0, T_2]$  and  $c' > 0$  which are independent of  $m$  such that

$$(4.13) \quad \|\nabla v_m\|_{L^2(\Omega)}^2 \leq c' \text{ for all } t \in [0, T'].$$

Q.E.D.

**§5. Proof of Theorem** (third step). In this section we examine the consequences obtained in §§3 and 4.

Let  $B_R$  be a closed ball in  $C^0([0, T'])^m$  with radius  $R \leq (c'/\lambda_1)^{1/2}$  and let  $(\tilde{a}_{m1}(t), \dots, \tilde{a}_{mm}(t)) \in B_R$ .

On the other hand, by (3.3), (4.13) and Poincaré's lemma, we find that

$$(5.1) \quad \sum_{k=1}^m a_{mk}^2(t) = \|v_m\|_{L^2(\Omega)}^2 \leq \frac{1}{\lambda_1} \|\nabla v_m\|_{L^2(\Omega)}^2 \leq \frac{c'}{\lambda_1} \leq R^2$$

and consequently

$$(5.2) \quad (a_{m1}(t), \dots, a_{mm}(t)) \in B_R \cap C^1([0, T'])^m.$$

Therefore we can conclude the map  $(\tilde{a}_{m1}(t), \dots, \tilde{a}_{mm}(t)) \rightarrow (a_{m1}(t), \dots, a_{mm}(t))$  is compact from  $B_R$  into itself and it has a fixed point. Namely this fixed point and  $\rho_m(t, x)$  defined by (3.6) solve (3.4) and (4.1) and satisfy the estimates obtained in §§3 and 4. Moreover it follows from these estimates that we can extract subsequences, still denoted by  $\rho_m$  and  $v_m$ , such that

$$(5.3) \quad \rho_m \rightarrow \rho \text{ weak* in } L^\infty([0, T'] \times \Omega)$$

and

$$(5.4) \quad v_m \rightarrow v \text{ weak* in } L^\infty(0, T'; H_\sigma^1(\Omega)) \text{ and weakly in } L^2(0, T'; H^2(\Omega))$$

and that

$$(5.5) \quad \|\rho_m\|_{L^\infty(0, T'; H^1(\Omega))} \leq c_7,$$

where  $c_7 > 0$  is independent of  $m$ .

**§6. Proof of Theorem** (fourth step). Let  $\Psi_m(t, x)$  and  $\theta_{0m}(x)$  be the regularization of  $\frac{\mu}{2} \sum_{j, k=1}^3 (v_{x_k}^j + v_{x_j}^k)^2$  and  $\theta_0(x) - \bar{\theta}$  respectively, where  $v$  is in (5.4), and consider the following initial-boundary value problem:

$$(6.1) \quad \begin{cases} c_{\sqrt{\rho_m}}(\theta_{mt} + \sum_{j=1}^3 v_m^j \theta_{mx_j}) = \kappa \Delta \theta_m + \Psi_m \\ \theta_m(0, x) = \theta_{0m}(x) \\ \theta_m|_{\partial\Omega} = 0. \end{cases}$$

Then this has a unique classical solution  $\theta_m(t, x)$  clearly. Moreover we have

**Lemma 6.1.** *There exists a constant  $\tilde{c} > 0$  independent of  $m$  such that*

$$(6.2) \quad \|\sqrt{\rho_m} \theta_m\|_{L^\infty(0, T'; L^2(\Omega))} + \|\theta_m\|_{L^2(0, T'; H_0^1(\Omega))} \leq \tilde{c}.$$

*Proof.* We can easily obtain the equality:

$$(6.3) \quad \frac{c_{\sqrt{\rho_m}}}{2} \int_{\Omega} \rho_m \theta_m^2 dx + \kappa \int_0^t \int_{\Omega} |\nabla \theta_m|^2 dx dt$$

$$= \frac{c_V}{2} \int_{\Omega} \rho_0 m \theta_m^2 dx + \int_0^t \int_{\Omega} \Psi_m \theta_m dx dt.$$

It follows from Hölder's inequality, Sobolev's imbedding theorem and the properties of mollifier that

$$(6.4) \quad \begin{aligned} & |\text{right hand side of (6.3)}| \\ & \leq c_8 \|v\|_{L^\infty(0, T; H^{\frac{1}{2}}(\Omega))}^2 \|v\|_{L^2(0, T; H^2(\Omega))}^2 \\ & + \frac{\kappa}{2} \|\nabla \theta_m\|_{L^2(0, T; L^2(\Omega))}^2 + \frac{c_V(M+1)}{2} \|\theta_0 - \bar{\theta}\|_{L^2(\Omega)}^2, \end{aligned}$$

where  $c_8 > 0$  is independent of  $m$ .

Therefore the desired estimate is accomplished. Q.E.D.

**§7. Proof of Theorem** (final step). In this section we shall consider the convergence of nonlinear terms as  $m \rightarrow \infty$ . For that purpose we rely on Lions[3].

The consequence that  $\rho_m$  is bounded in  $L^2([0, T'] \times \Omega)$ ,  $v_m$  is bounded in  $L^2(0, T'; H^1(\Omega))$  and  $\rho_m t$  is bounded in  $L^2(0, T'; H^1(\Omega))$  and the compensated compactness imply that  $\rho_m v_m \rightarrow \rho v$  and  $\rho_m \theta_m \rightarrow \rho \theta$  in the sense of distributions.

Next it follows from estimates obtained in §§3, 4 and 5 that  $\rho_m v_m^j$  is bounded in  $L^2(0, T'; L^6(\Omega))$  and  $(\rho_m v_m^j)_t$  is bounded in  $L^2(0, T'; H^1(\Omega))$ ,  $j=1, 2, 3$ . Thus we can extract a subsequence, still denoted by  $\rho_m v_m^j$ , such that  $\rho_m v_m^j \rightarrow \xi$  weakly in  $L^2(0, T'; L^6(\Omega))$ . Therefore the compensated compactness implies that  $\rho_m v_m^j v_m \rightarrow \xi v$  and  $\rho_m v_m^j \theta_m \rightarrow \xi \theta$ ,  $j=1, 2, 3$ , in the sense of distributions. But we have already shown that  $\xi = \rho v^j$ . So we find that the limit functions  $\rho(t, x)$ ,  $v(t, x)$  and  $\theta(t, x)$  satisfy the conditions in Definition.

This completes the proof of Theorem.

## References

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